M2D Gyro Stabilized Gimbal ball turret for Suas, UAV, multicopter, hexacopter, unmanned drones Cameras' Pinout Ver 1.0

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Table of Content

1 Overview

The document describes the pinout of the M2-D camera.

2 Connector

The cameras are interfaced using single 1.25mm pitch 10-pin header connector (Molex 53047-1010) which carries power, control and video signals.

The wire harness connecting to the camera should include Molex (51021-1000) (10 pos / 1.25mm) connector.

2.1 Numbering plan

The numbering plan of the camera header connector (Molex 53047-1010) is depicted in Figure 1:

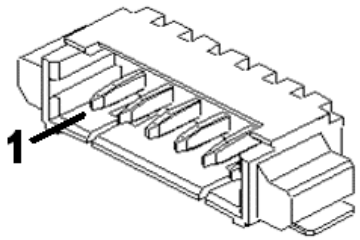

Figure 1: Camera Header Connector Numbering Plan

The numbering plan of the cable connector (Molex 51021-1000) is depicted in Figure 2:

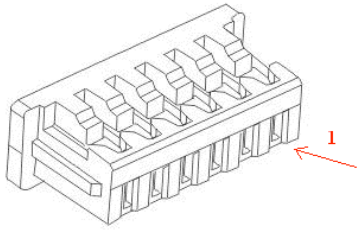

Figure 2: Wire Housing Connector Numbering Plan

2.2 Pin Assignment

The pin assignment is depicted in the following table:

Pin	NAME	DIR	Description
1	SYS_PWR	IN	System Power Input
2	GND	-	System Ground
3	RS232_IN	IN	RS232 Receive Input
4	RS232_OUT	OUT	RS232 Transmitter Output
5	GND	-	RS232 Ground
6	Reserved	-	Do not connect
7	Reserved	-	Do not connect

8	GND	-	System Ground
9	VIDEO_OUT	OUT	Video Out (PAL or NTSC)
10	VIDEO_GND	-	Video Ground

2.3 Power Supply

Note

Power supply range is specified at camera connector. One should consider the voltage drop on the wires connecting the camera to the power supply. Using +12VDC power supply is recommended.

Warning

The camera will be seriously damaged if power exceeds the maximum allowed voltage

The camera will be seriously damaged if power polarity is reversed

The camera will be seriously damaged if power is applied to video port